



ROBOSUB – TEAM 4

Requirements and Needs Analysis

October 2014

Dennis Boyd

- Lead Programmer, Web designer
 - Primary programmer
 - Develop and maintain the webpage



Elliot Mudrick

Bjorn Campbell

- Treasurer, Electrical systems
 - Responsible for money
 - Acquisition of parts
 - Power and heat distribution in the sub
 - Circuit design



Elliot Mudrick

Samantha Cherbonneau

- Programmer, Secretary
 - Documents group minutes
 - Manages and finalizes documents
 - Responsible for writing code allocated by lead programmer



Elliot Mudrick

Kevin Matungwa

- Programmer, Vice Team Leader
 - Assumes team leader responsibilities when required
 - Responsible for writing code allocated by lead programmer



Elliot Mudrick

Elliot Mudrick

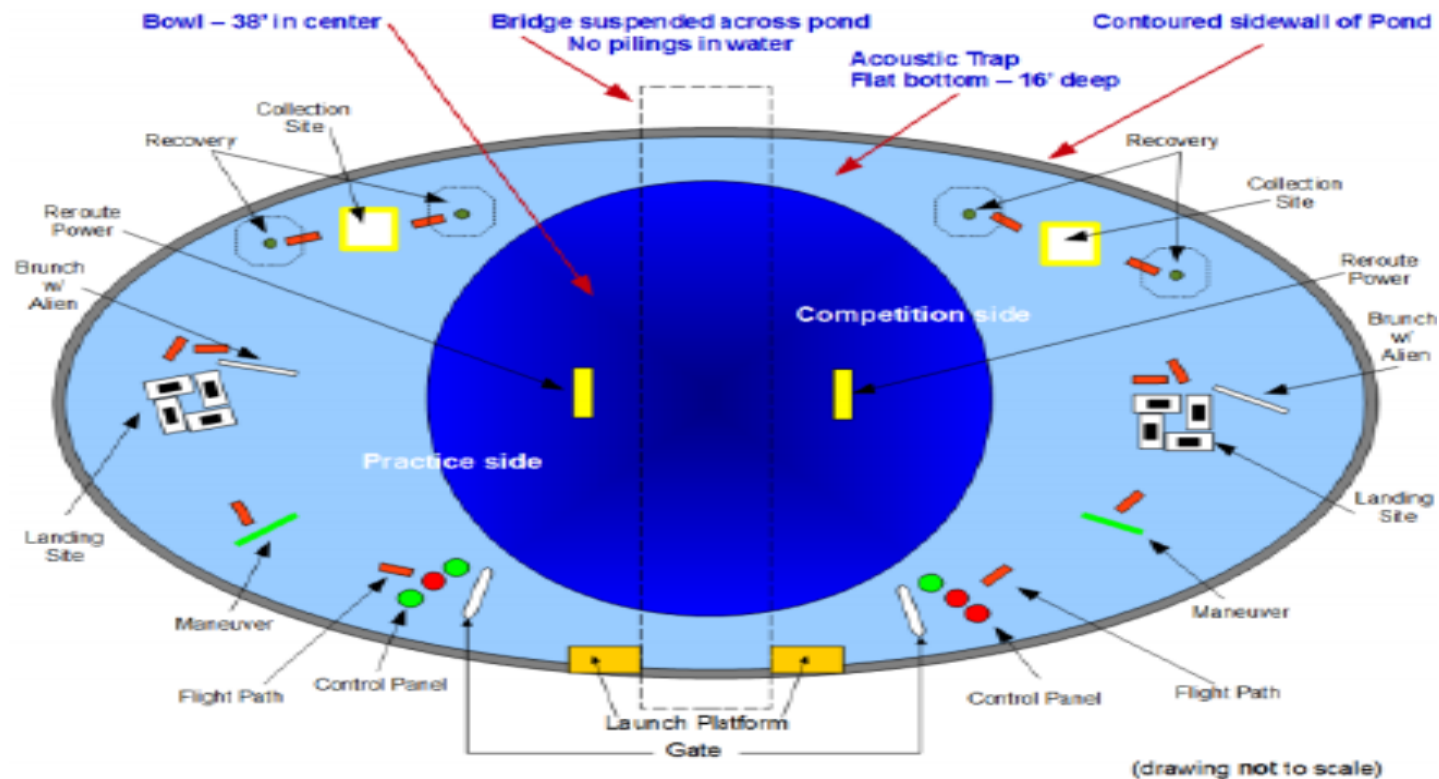
- Team leader, Programmer, Web designer
 - Responsible for timelines
 - Team coordination
 - Programming tasks assigned by lead programmer
 - Develop and maintain the webpage



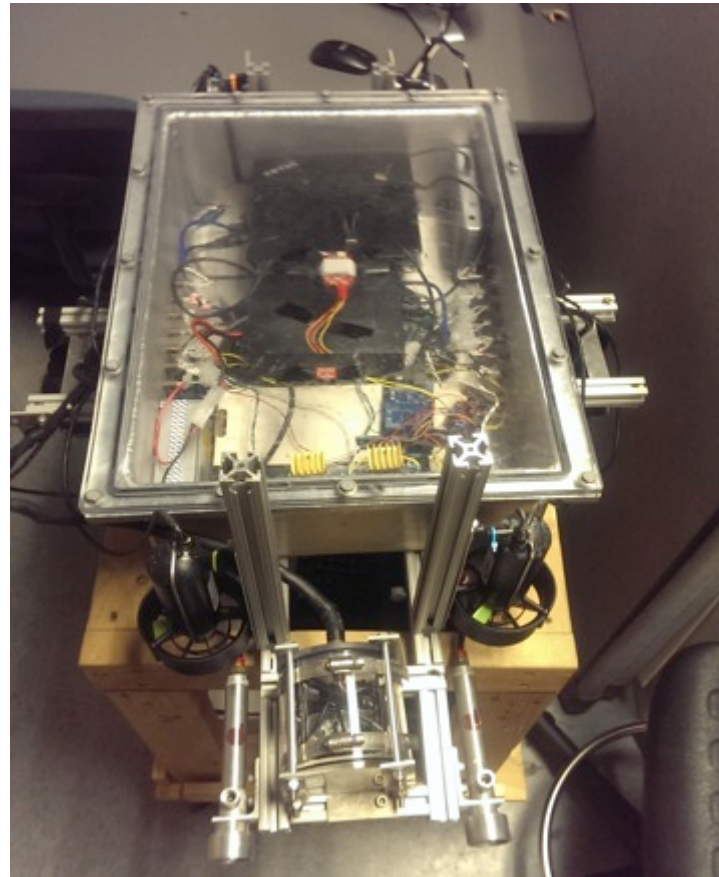
Elliot Mudrick

Overview of the RoboSub Competition

- Association for Unmanned Vehicle Systems International (AUVSI)



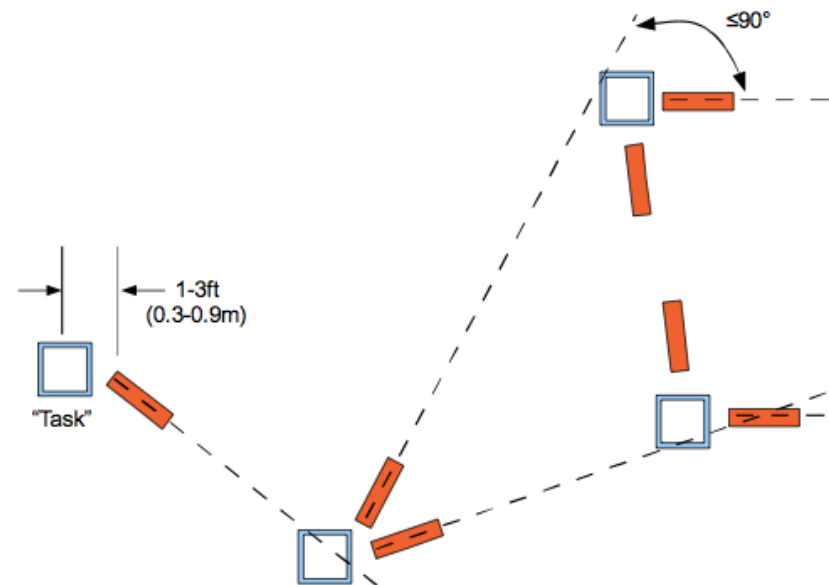
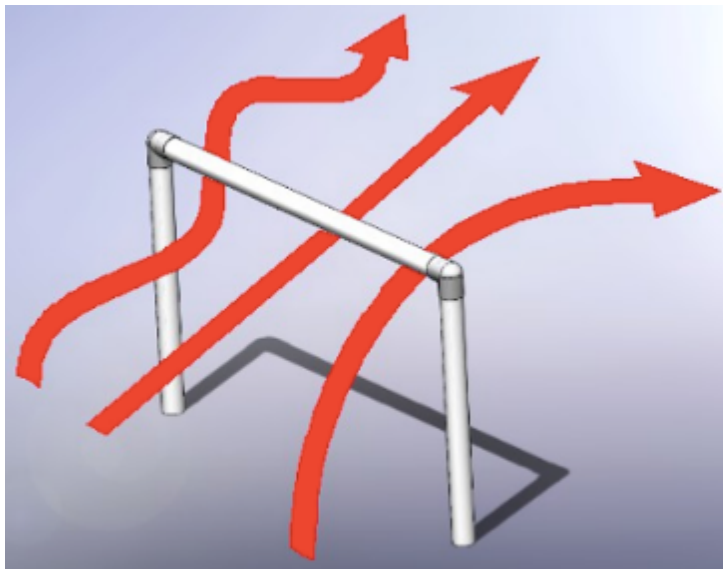
Overview of the Current RoboSub



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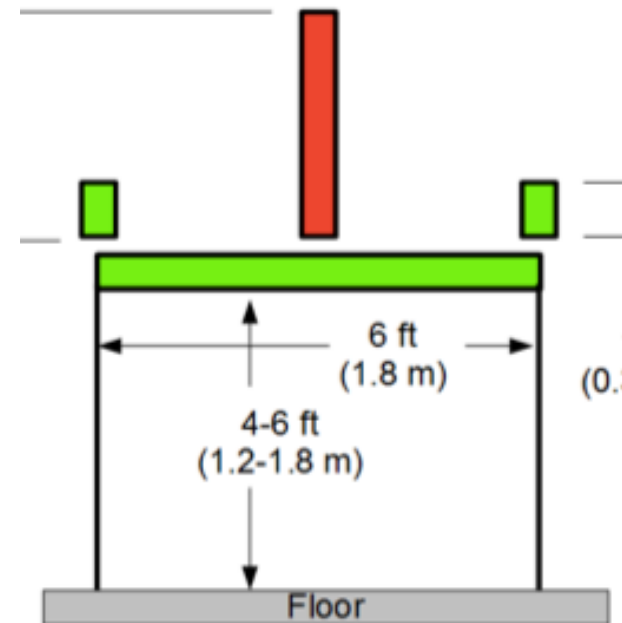
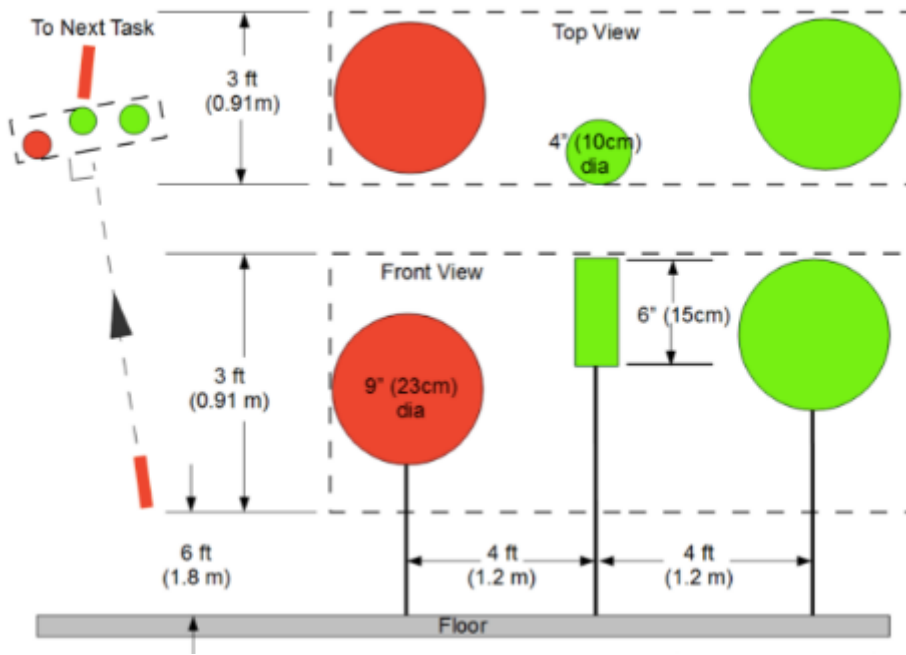
Required Capabilities

- Run autonomously
- Pass through the validation gate
- Follow a path of orange line segments that guide the sub between tasks



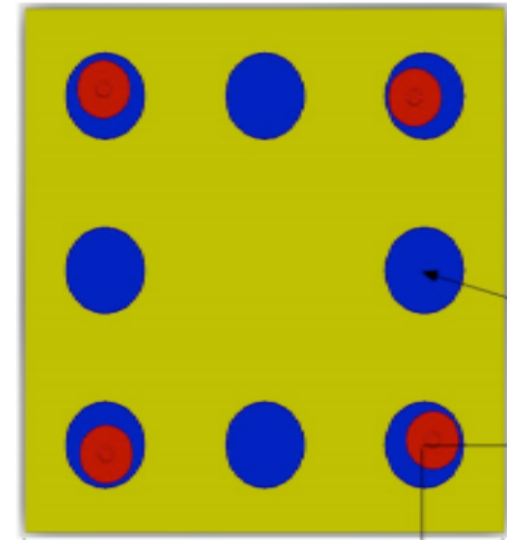
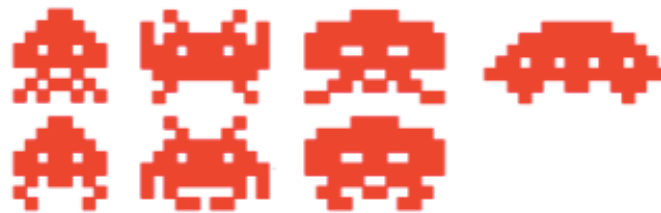
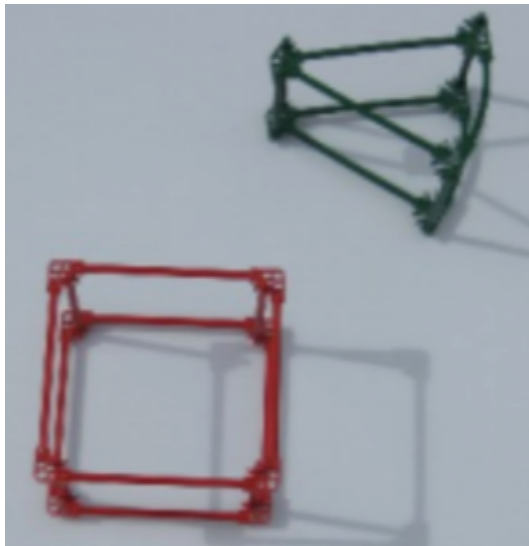
Desired Capabilities

- Movement & Color Recognition
 - Bump a buoy until on proper LED color
 - Maneuver around/over PCV based on color and location of risers



Desired Capabilities

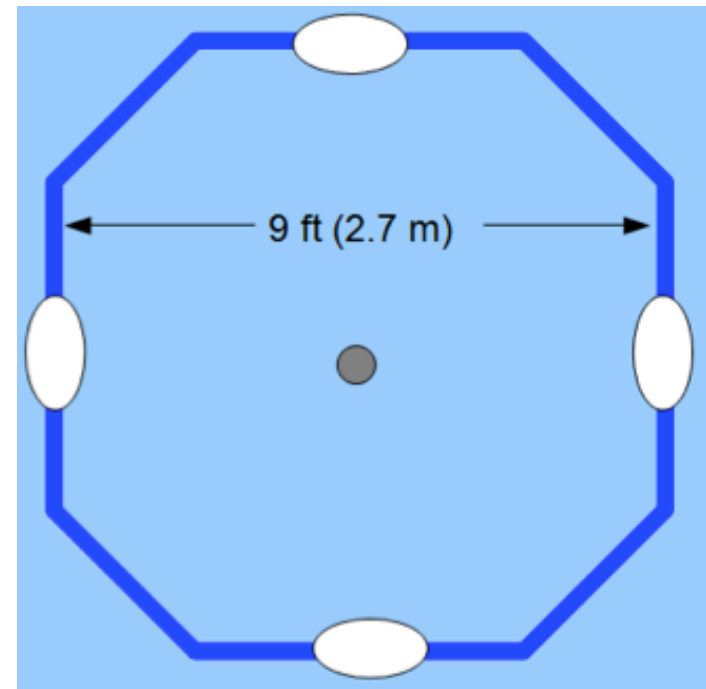
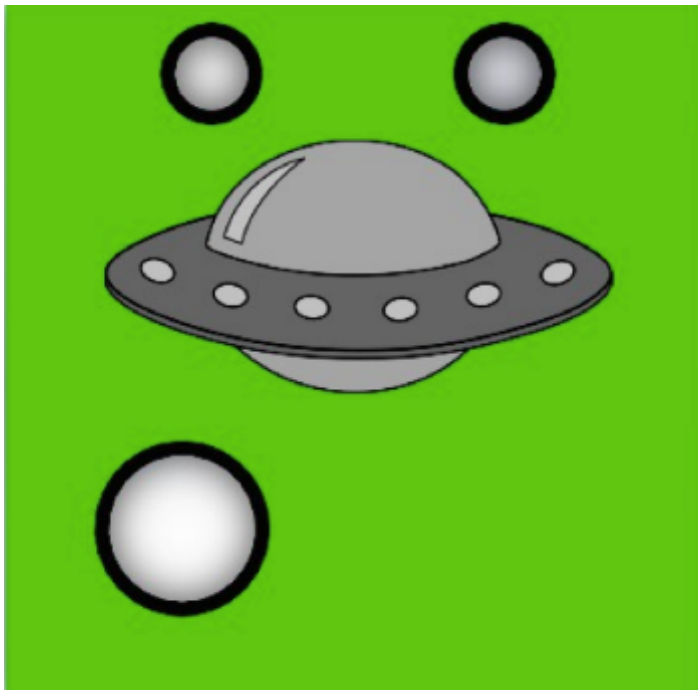
- Gripping, Shape & Color Recognition
 - Drop marker in a bin with primary alien target, another in a bin with secondary alien target
 - Grab colored objects and deliver to box
 - Remove power pins and then place back



Sam Cherbonneau

Desired Capabilities

- Precision
 - Fire a torpedo through a small hole in a target
 - Surface inside octagon based on acoustic pinger placement



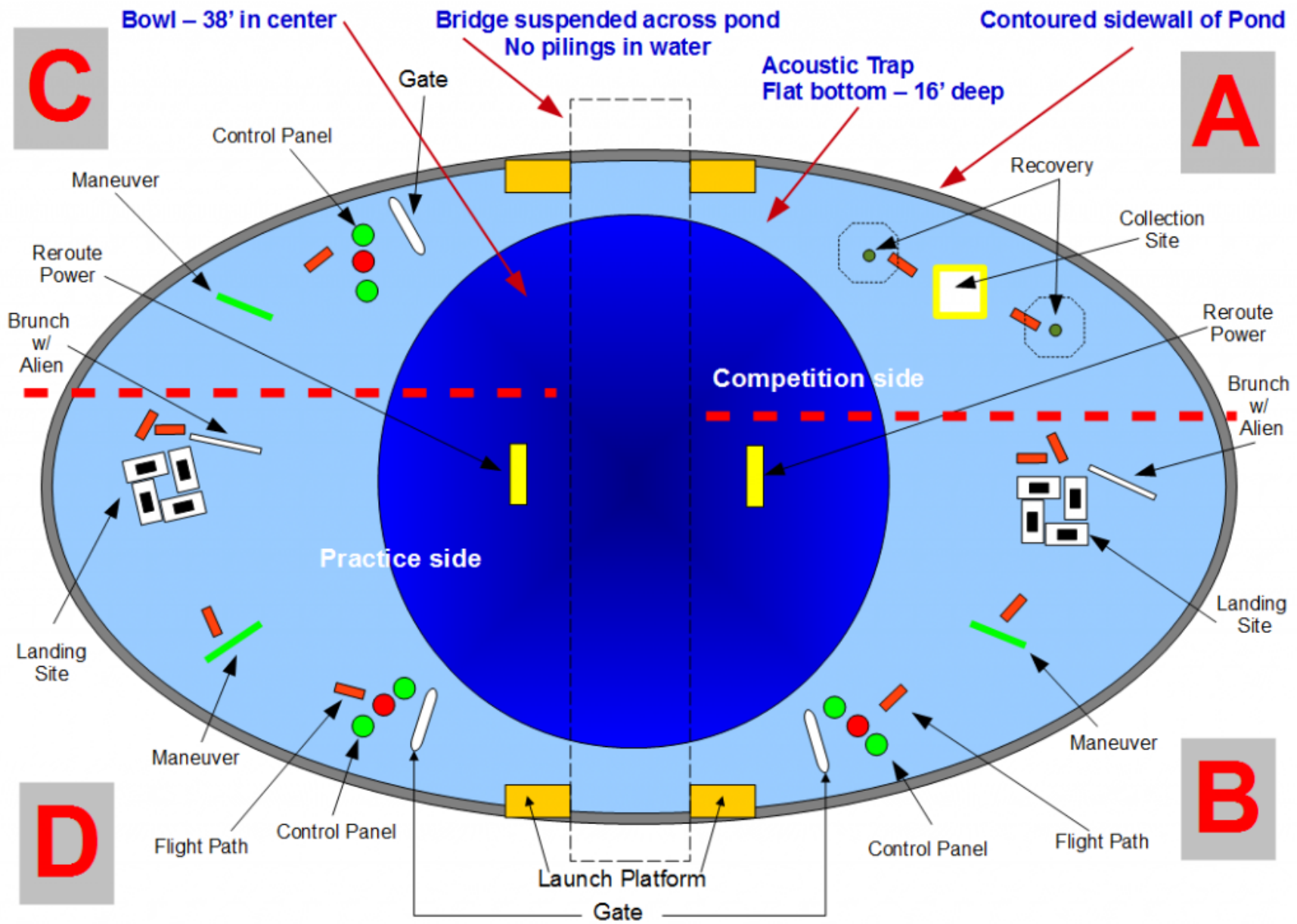
Functional Requirements

- Path
- Control Panel Buoy
- Maneuvering
- Landing Site
- Brunch
- Reroute Power
- Recovery Area
- Interference
- Acoustics

Path

- Consists of Line Segments
- Made of Aluminum Sheets
 - 6" wide by 4' long
 - Raised off the floor 1'-2'
 - Blaze Orange Duke tape
- Line Segments are like Arrows
- Start at the Control Panel
 - Maneuvering area
 - Landing Site/Brunch
 - 2 Different paths
 - One points to Reroute Power
 - One Points to Recovery area



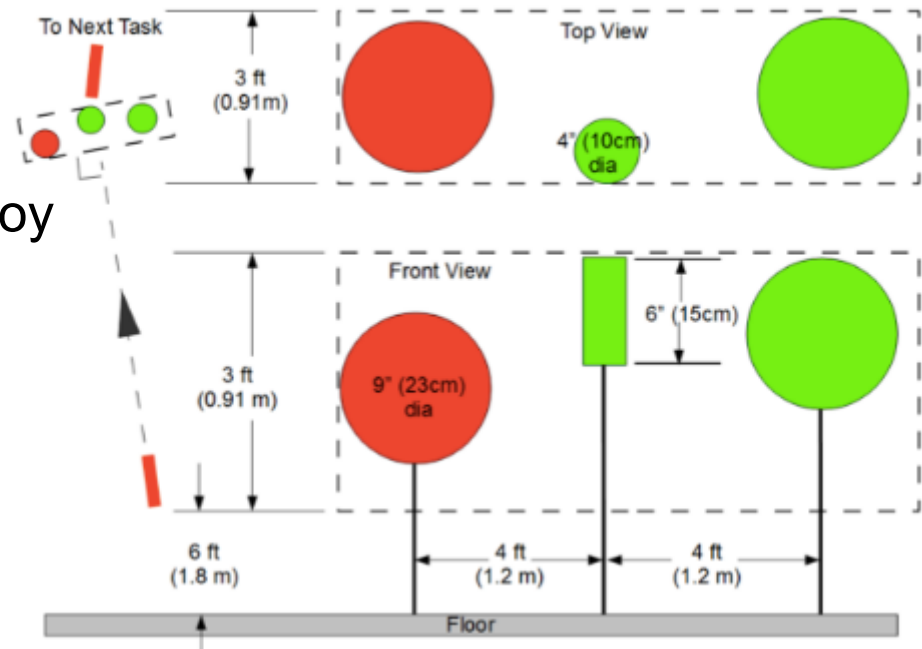


Bjorn Campbell

Control Panel

- 3 Moored Buoys

- RED/GREEN/BLUE (RGB) buoy
 - 4" diameter and 15" long
- RED buoy
 - 9" diameter
- GREEN Buoy
 - 9" diameter



- RGB buoy Cycles through Red and Green every 5 seconds
 - Most points received by turning the RGB buoy Green
 - Points awarded for touching the Red then the Green Buoy

Maneuvering

- Platform

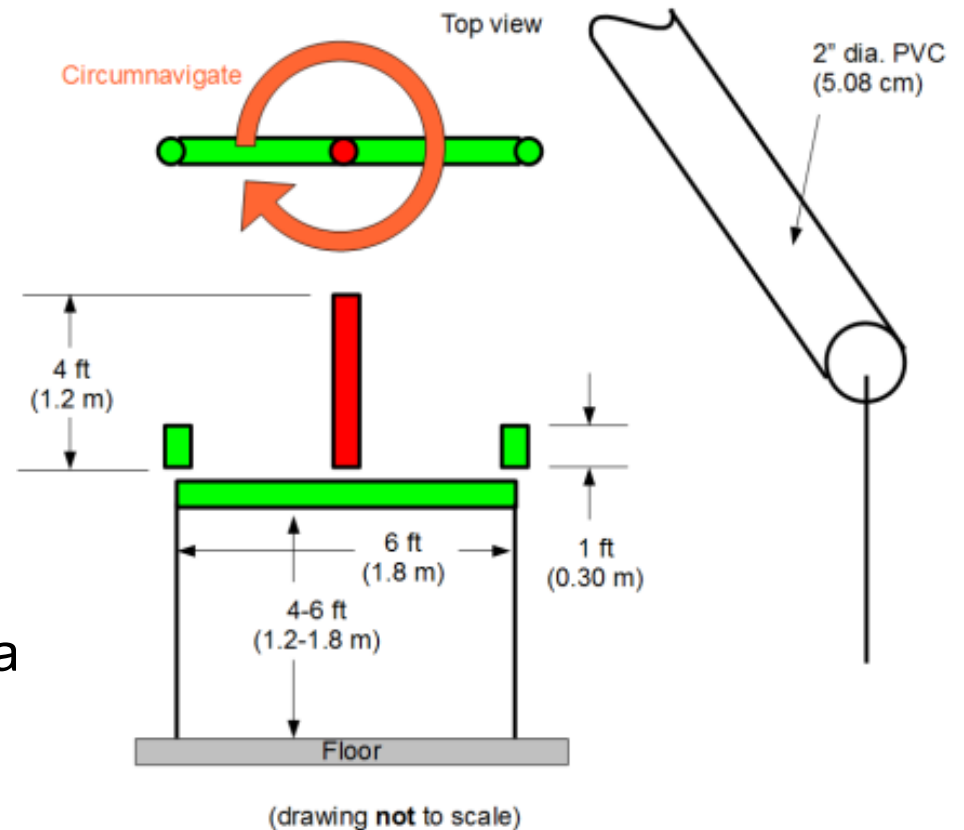
- 6' long 2" diameter PVC Pipe
- 1' Raisers on the Sides
- 4' long 2" diameter PVC pipe Center A

- 2 Different ways to Navigate

- First move your sub between a side ledge and the Center

OR

- Circumnavigate around the center PVC

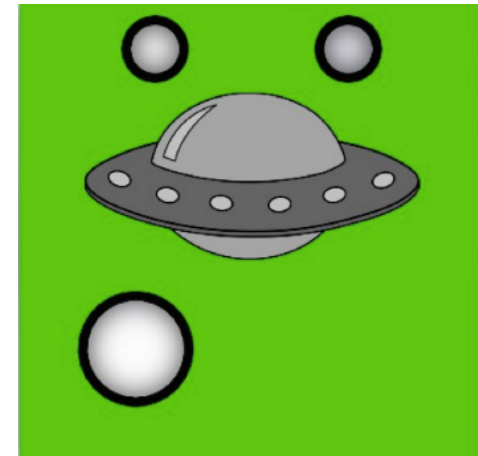


Landing Site / Brunch

- Landing Site
 - BLACK bins surrounded by a white border.
 - Drop Markers into the Primary Bin
 - Primary Bin determined by an Alien silhouette.

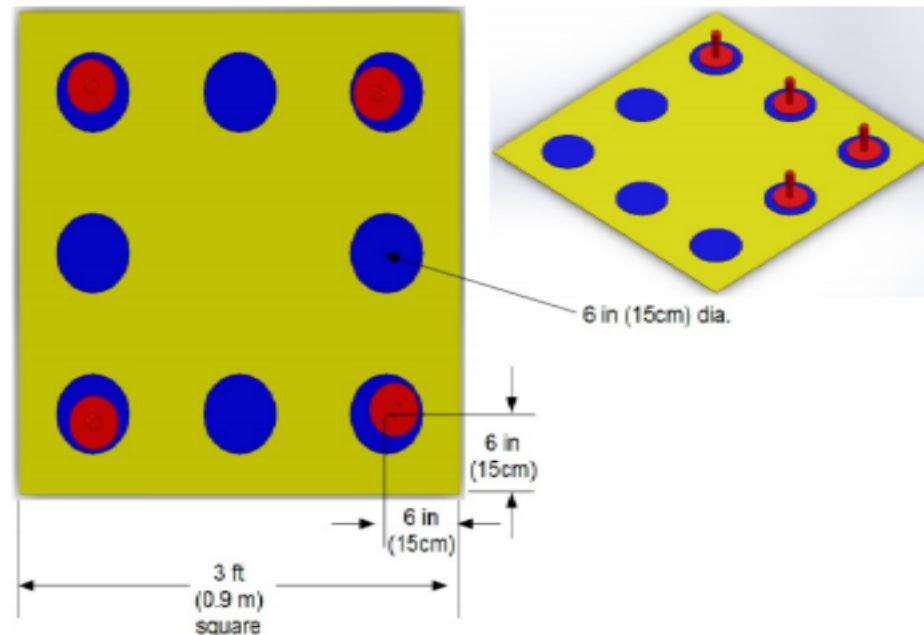


- Brunch
 - Single Square Green Board
 - Spacecraft in the center
 - Above the Spacecraft are 4X5" holes with 7" black borders
 - Below the Spacecraft are 2X10" holes with 12" black borders



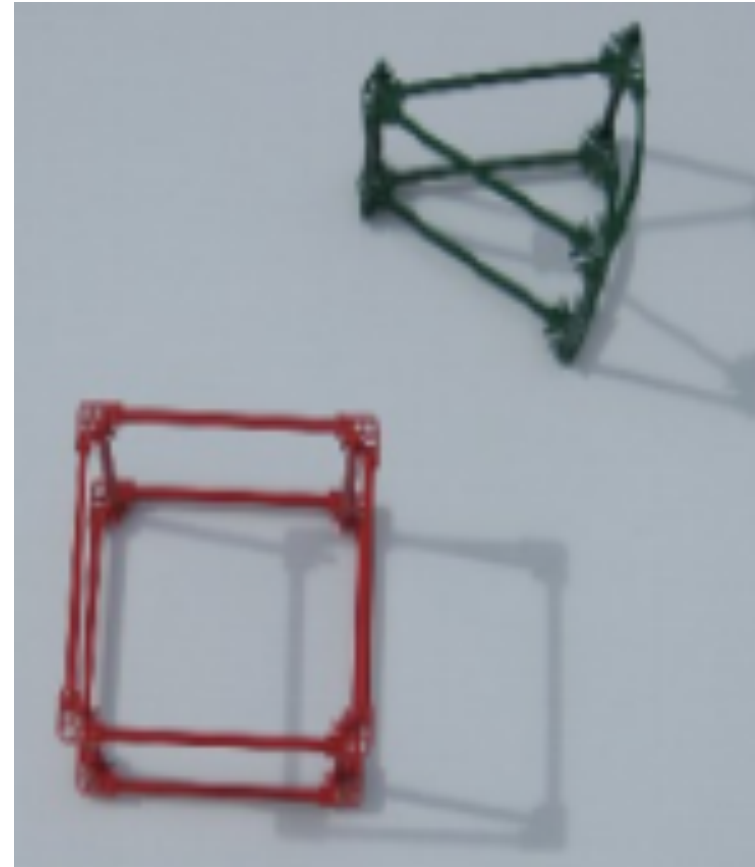
Reroute Power

- 8 Blue circles arranged on a 36" yellow square
- 4 Red Power Pins
- Remove 1 Red Power Pin and place the Power Pin in an unoccupied blue circle



Recovery

- Two different Recovery Areas
- Directly above Acoustic pinger will determine the location of the Sample Box
- Recovery Area is an Octagon of $\frac{1}{2}$ " PVC pipe in a "diameter" of 9 ft
- Travel to Collection Site by Path line
- Remove mars rocks/cheese from the Collection Site and place them in the Sample Box.



Interference / Acoustic Pinger

- Interference
 - The AUV will not interfere with course components otherwise disqualification can occur.
- Acoustic Pinger:
 - Teledyne Benthos ALP-365 pingers
 - They can be set from 25-40 kHz in 0.5 kHz increments.

Non-Functional Competition Requirements

- Journal Paper
 - 10 Pages describing the rationale behind the design.
 - Video introducing the team, the sub, and strategies for the competition
- Resumes
 - Zipped to the Journal Paper.
 - Encouraged by AUVSI
 - Benefit to the Competitors

Constraints

- Based on the 2014 Competition
- Will be different this year (hopefully similar)
- Set ground rules for what sub can compete
- Will dictate how certain components and systems may be designed



Weight Constraints

- The below table will determine the weight requirements of the AUV:

Table 1: Size and weight constraints on AUVs entered into the competition.		
	Bonus	Penalty
AUV Weight > 125 lbs (AUV Weight > 56.7 kg)	N/A	Disqualified!!!
125 lbs ≥ AUV Weight > 84 (56.7 kg ≥ AUV Weight > 38 kg)	N/A	Loss of 250 + 5(lb – 125) 250 + 11(kg – 56.7)
84 lbs ≥ AUV Weight > 48.5 (38 kg ≥ AUV Weight > 22 kg)	Bonus of 2(84 – lb) 4.4(38-kg)	N/A
AUV Weight ≤ 48.5 lbs (AUV Weight ≤ 22 kg)	Bonus of 80 + (48.5 – lb) 80 + 2.2(22-kg)	N/A

- Required: ≤ 125 pounds

Basic Constraints

- Only one vehicle per team.
- Judges may disqualify a vehicle for unreasonable safety hazards.
- Vehicles must operate autonomously.
- All vehicles are battery powered. All batteries must be sealed. Maximum DCV will not exceed 60 V for the batteries or battery systems.
 - Significant restraint for computer, controllers, motors, etc.

Marker & Torpedo Constraints

- Each marker must fit within a box 2.0” square and 6” long.
 - Each must weigh less than 2.0 lbs.
 - Each marker must bear the team name or an emblem.
- Torpedoes must not be loaded in team tents.
- The torpedoes size, weight, markings are identical to the Markers.
 - The torpedoes must travel at a “safe” speed.

Kill Switch Constraint

- All vehicles must have a kill switch that a diver can readily activate.
- All vehicles must be buoyant by at least 0.5% of their mass when they have been shut off through the kill switch.
 - Important design requirement



Dennis Boyd

Additional Safety Constraints

- Judges will disqualify any vehicle that poses an unreasonable risk to the integrity of the host facility.
- No materials (except for the markers/torpedoes and compressed air used to blow ballast) may be released by the vehicle into the waters of the arena.
- For the safety of your vehicle, we require it to be slung on a harness or sling of some type.

Capabilities Test Plan

- **Path**
 - Test by placing orange tape marker in the pool
- **Control Panel**
 - Use LED lights to ensure the sub recognizes the buoy
- **Maneuvering**
 - Build test gate and ensure robot can maneuver successfully

Capabilities Test Plan

- **Landing Site**
 - Build 2 boxes and ensure the sub can drop markers in each accordingly (primary and secondary)
- **Brunch**
 - Ensure sub can fire torpedoes through an open hole using the camera vision
- **Reroute Power**
 - Construct a board with two circles and verify robot can grab and remove pin, and preferably return to same circle
- **Recovery Area**
 - Construct following Mars Rock and Green Cheese and ensure the robot can do the following
 - Recognize and follow an acoustic pinger
 - Grab the rock and cheese within 3 degrees of freedom
 - Follow orange tape to collection site when guided by pinger
 - Carry rocks or cheese and release at top

Constraints Test Plan

- **Sub, Markers, and Torpedoes Weights**
 - Separately measure dry weight of sub, markers, and torpedoes on a scale to ensure less than 125 lbs, 2 lbs, and 2 lbs, respectively
- **Marker and Torpedo Dimensions**
 - Use tape measure to ensure markers and torpedoes are within 5.08x5.08x15.24cm box each
- **Torpedo Travel Speed**
 - Test torpedoes in pool to ensure they are moving at a safe speed

Preliminary Budget

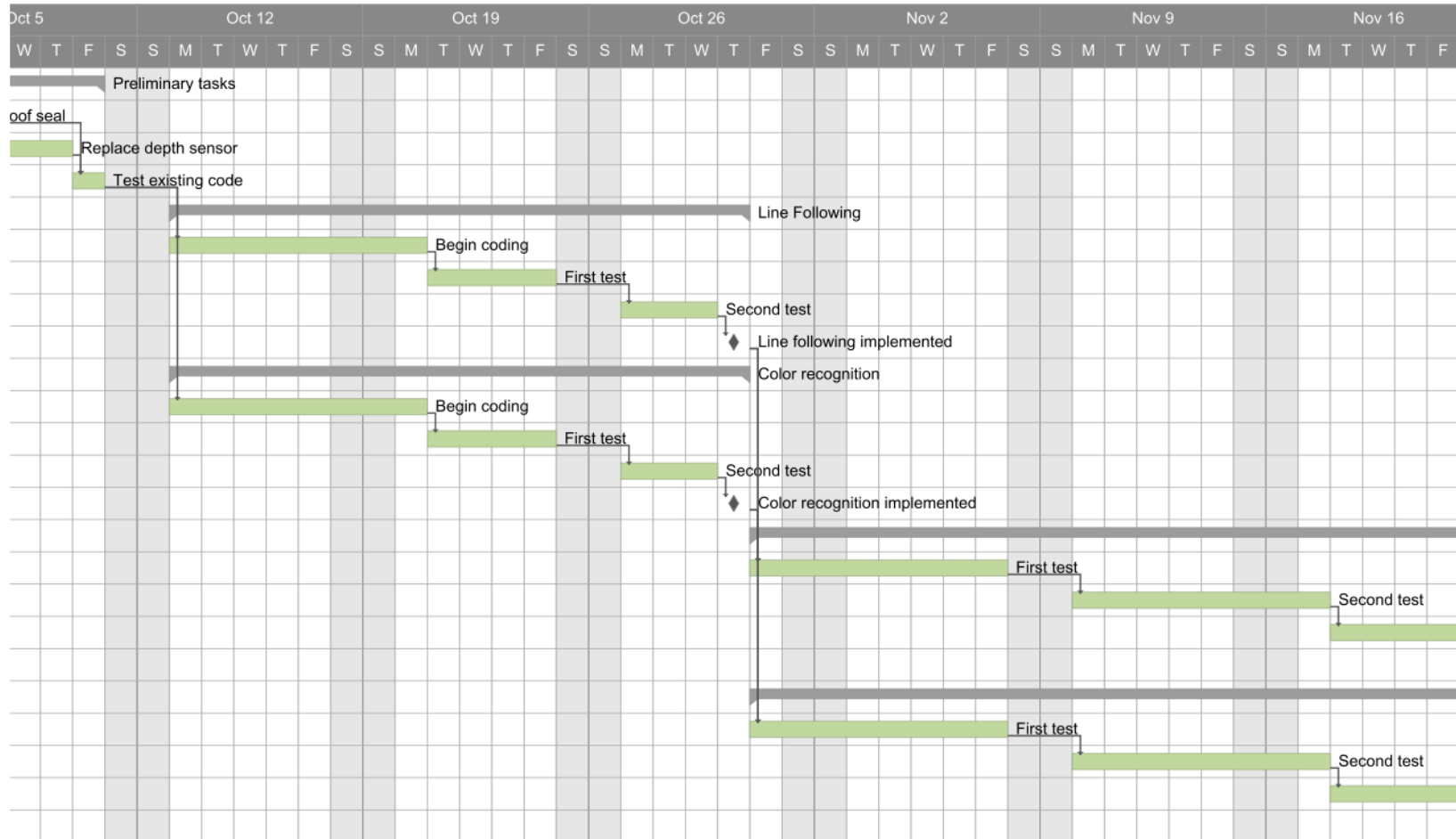
- Roughly \$250
- Need to Purchase Immediately
 - Depth Sensor
 - Chargeable Battery
 - Waterproof Seal Around Sub (most likely)
- Desired Purchases
 - Functional Gripper Arm
 - Torpedoes
 - Pinger Sensor
 - *Note: Will wait to purchase until we receive formal requirements for competition*



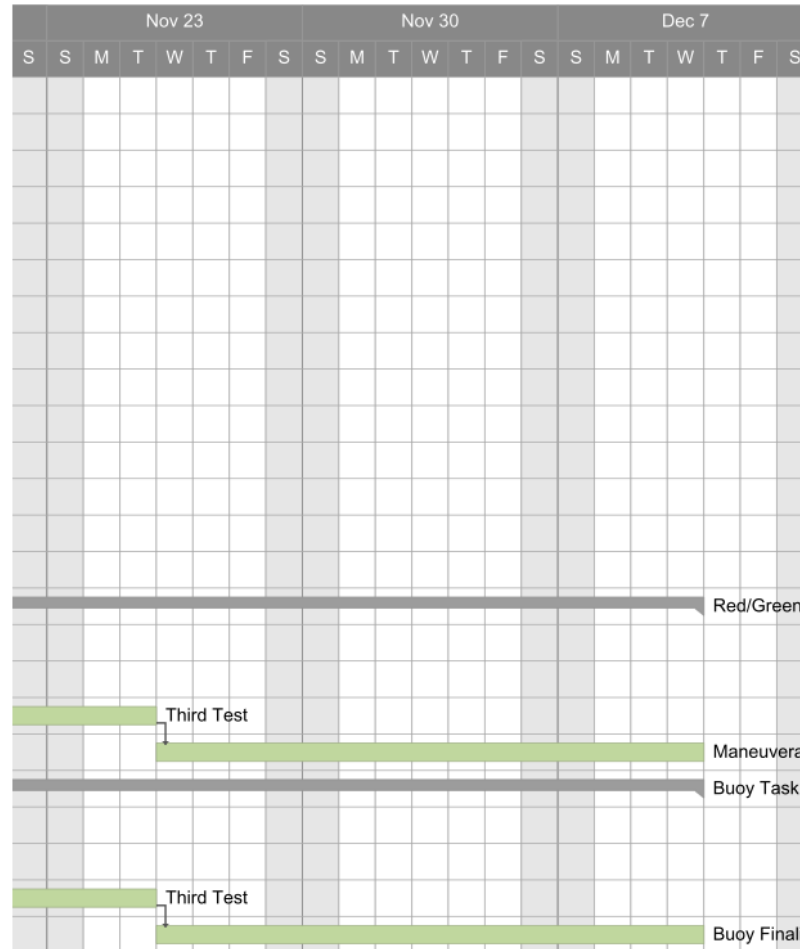
Preliminary Schedule

Task Name	Start Date	End Date	Predecessors	Sep 21							Sep 28								
				S	M	T	W	T	F	S	S	M	T	W	T	F	S	S	M
1 Preliminary tasks	09/25/14	10/10/14																	
2 Test waterproof seal	10/04/14	10/04/14																	
3 Replace depth sensor	09/25/14	10/09/14																	
4 Test existing code	10/10/14	10/10/14	2, 3																
5 Line Following	10/13/14	10/30/14																	
6 Begin coding	10/13/14	10/20/14	4																
7 First test	10/21/14	10/24/14	6																
8 Second test	10/27/14	10/29/14	7																
9 Line following implemented	10/30/14	10/30/14	8																
10 Color recognition	10/13/14	10/30/14																	
11 Begin coding	10/13/14	10/20/14	4																
12 First test	10/21/14	10/24/14	11																
13 Second test	10/27/14	10/29/14	12																
14 Color recognition implemented	10/30/14	10/30/14	13																
15 Red/Green PVC Maneuverability Task	10/31/14	12/10/14																	
16 First test	10/31/14	11/07/14	9, 14																
17 Second test	11/10/14	11/17/14	16																
18 Third Test	11/18/14	11/25/14	17																
19 Maneuverability Finalized	11/26/14	12/10/14	18																
20 Buoy Task	10/31/14	12/10/14																	
21 First test	10/31/14	11/07/14	9, 14																
22 Second test	11/10/14	11/17/14	21																
23 Third Test	11/18/14	11/25/14	22																
24 Buoy Finalized	11/26/14	12/10/14	23																

Preliminary Schedule



Preliminary Schedule



Preliminary Risk Assessment

- Risks to Sub
 - Water damage
 - Overheating
 - Dry rot
 - Shatter/Crack if pressure is too high
- Risk to Persons
 - Exposed wires in water could lead to electrocution
 - Drowning during testing

Questions?

